

Mixed Problem for one Class Semilinear Fourth-order Hyperbolic Systems

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Abstract. Mixed problem for systems of fourth-order semilinear hyperbolic equations is considered, when fourth and second-order derivatives with different variables participate in each equation. The theorem on local solvability is proved. Further, for a class of semilinear fourth-order systems, the theorem on solvability "as a whole" is proved.

Key Words and Phrases: semilinear hyperbolic equation, mixed problem, solvability

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1. Statement of the problem and the main result on local solvability

Consider the systems of semilinear hyperbolic equations of the fourth order

$$\left. \begin{aligned} u_{1tt} + \Delta_{I_1}^2 u_1 - \Delta_{J_1} u_1 &= f_1(t, x, u_1, u_2), \\ u_{2tt} + \Delta_{I_2}^2 u_2 - \Delta_{J_2} u_2 &= f_2(t, x, u_1, u_2), \end{aligned} \right\} \quad (1)$$

where $\Delta_{I_k} = \sum_{i \in I_k} \frac{\partial^2}{\partial x_i^2}$, $\Delta_{J_k} = \sum_{i \in J_k} \frac{\partial^2}{\partial x_j^2}$, $I_k \subset N_n = \{1, \dots, n\}$, $J_k = N_n \setminus I_k$, $k = 1, 2$.

Let us denote by $m_r = \overline{J_r}$, $r = 1, 2$ the number of elements J_r , and denote by $n_r = \overline{I_r} = n - m_r$ the number of elements I_r . For definiteness, suppose that

$$m_1 \leq m_2. \quad (2)$$

A system of type (1) is encountered in the study of oscillations of deformed systems under moving loads (see e.g. [1]). In [2], the Cauchy problem for systems of equations

$$\left. \begin{aligned} u_{1tt} + \Delta_{I_1}^2 u_1 - \Delta_{J_1} u_1 + u_{1t} &= g_1(u_2), \\ u_{2tt} + \Delta_{I_2}^2 u_2 - \Delta_{J_2} u_2 + u_{2t} &= g_2(u_1), \end{aligned} \right\}$$

is investigated, where

$$|g_1(u_2)| \leq |u_2|^p, \quad |g_2(u_1)| \leq |u_1|^q,$$

and found conditions for the growth of coefficients p, q ensuring the existence of global solutions.

In this paper we study the existence and uniqueness of local and global solutions of a mixed problem for the system (1).

Let $\Pi = [0, 1]^m$. In the cylinder $Q_T = [0, T] \times \Pi$ we consider the mixed problem for system (1) with the boundary conditions

$$u_k(t, x_1, x_2, \dots, x_i, \dots, x_n) = 0, \quad x_i = 0, x_i = 1, k = 1, 2; \quad i = 0, 1, \dots, n; \quad (3)$$

$$\Delta_{I_k} u_k(t, x_1, x_2, \dots, x_i, \dots, x_n) = 0, \quad x_i = 0, x_i = 1, i \in I_k, \quad k = 1, 2; \quad (4)$$

and the initial conditions

$$u_k(0, x) = \varphi_k(x), \quad u_{kt}(0, x) = \psi_k(x), \quad x \in \Pi, \quad k = 1, 2. \quad (5)$$

By $W_{2,k}^{2s,s}$, $k = 1, 2$ denote the functional space with a finite norm:

$$\|u\|_{W_{2,k}^{2s,s}}^2 = \left\{ \|u\|_{L_2(R_N)}^2 + \sum_{i \in I_k} \|D_{x_i}^{2s} u\|^2 + \sum_{j \in J_k} \|D_{x_j}^s u\|^2 \right\}^{\frac{1}{2}},$$

and by H denote the functional space $H = W_{2,1}^{2,1} \times L_2(R^n) \times W_{2,2}^{2,1} \times L_2(R^n)$, with the scalar product

$$\begin{aligned} \langle w^1, w^2 \rangle_H = & \int_{\Pi} \Delta_{I_1} v_1^1 \Delta_{I_1} v_1^2 dx + \int_{\Pi} \nabla_{J_1} v_2^1 \nabla_{J_1} v_2^2 dx + \\ & + \int_{\Pi} \Delta_{I_2} v_3^1 \Delta_{I_2} v_3^2 dx + \int_{\Pi} \nabla_{J_2} v_4^1 \nabla_{J_2} v_4^2 dx. \end{aligned}$$

Let us assume that

$$n + m_2 < 4. \quad (6)$$

and the following condition holds.

I. The functions $f_1(t, x, \xi, \eta)$ and $f_2(t, x, \xi, \eta)$ are defined for all $t \in [0, T]$, $x \in \Pi$, $\xi \in R$, $\eta \in R$ and continuously differentiate with respect to t , ξ and η ;

The following theorem on local solvability is proved.

Theorem 1. *Let (2), (6) and the condition I be satisfied. Then for any $(\varphi_1, \psi_1, \varphi_2, \psi_2) \in H$ there exists $T' > 0$ such that the problem (1), (3) - (5) has a unique solution $(u_1, u_2) \in C([0, T']; W_{2,1}^{2,1} \times W_{2,2}^{2,1}) \cap C^1([0, T']; L_2(\Pi) \times L_2(\Pi))$.*

Moreover, if T_{\max} - the length of the maximal interval of the existence of a weak solution is $(u_1, u_2) \in C([0, T_{\max}); W_{2,1}^{2,1} \times W_{2,2}^{2,1}) \cap C^1([0, T_{\max}); L_2(\Pi) \times L_2(\Pi))$, then one of the following statements hold:

i) or $T_{\max} = +\infty$,

ii) or $\lim_{t \rightarrow T_{\max} - 0} E(t) = +\infty$, where

$$E(t) = \sum_{k=1}^2 \left[\|u_k(t, \cdot)\|_{W_{2,k}^{2,1}} + \|u'_{kt}(t, \cdot)\|_{L_2(R^n)} \right], \quad t \in [0, T_{\max}).$$

If additionally $(\varphi_1, \psi_1, \varphi_2, \psi_2) \in W_{2,1}^{4,2} \times W_{2,1}^{2,1} \times W_{2,2}^{4,2} \times W_{2,2}^{2,1}$, then

$$(u_1, u_2) \in C\left([0, T']; W_{2,1}^{4,2} \times W_{2,2}^{4,2}\right) \cap C^1\left([0, T']; W_{2,1}^{2,1} \times W_{2,2}^{2,1}\right) \cap \\ \cap C^2\left([0, T']; L_2(R^n) \times L_2(R^n)\right).$$

Now consider the case $n + m_2 \geq 4$. In this case, the following condition on the growth of nonlinearity is required. First let us consider the case $n + m_1 < 4$

II. a) Let $n + m_1 < 4$, $n + m_2 \geq 4$ and for all $(t, x, \xi, \eta) \in [0, T] \times \Pi \times R^2$ the following estimates are fulfilled

$$|f_k(t, x, \xi, \eta)| + |f'_{kt}(t, x, \xi, \eta)| \leq c(\xi) [g_k(x) + |\eta|^{p_k}],$$

$$|f'_{k\xi}(t, x, \xi, \eta)| \leq c(\xi) [h_k(x) + |\eta|^{q_k}],$$

$$|f'_{k\eta}(t, x, \xi, \eta)| \leq c(\xi) [h_k(x) + |\eta|^{q_k}],$$

where $c(\cdot) \in C(R; R_+)$, $g_k(\cdot) \in L_2(\Pi)$,

if $n + m_2 = 4$ then $p_k \in [1, \infty)$ and if $n + m_2 > 4$ then $p_k \leq \frac{n + m_2}{n + m_2 - 4}$.

II b) Let $n + m_1 \geq 4$ and for all $(t, x, \xi, \eta) \in [0, T] \times \Pi \times R^2$ satisfy the following estimations

$$|f_k(t, x, \xi, \eta)| + |f'_{kt}(t, x, \xi, \eta)| \leq c [g_k(x) + |\xi|^{p_{k1}} + |\eta|^{p_{k2}}]$$

$$|f'_{k\xi}(t, x, \xi, \eta)| \leq c [h_k(x) + |\xi|^{q_{k1}} + |\eta|^{q_{k2}}];$$

$$|f'_{k\eta}(t, x, \xi, \eta)| \leq c [l_k(x) + |\xi|^{r_{k1}} + |\eta|^{r_{k2}}],$$

where $c \in R_+ = [0, \infty)$, $g_k(\cdot) \in L_2(\Pi)$, and $h_k(\cdot), l_k(\cdot), p_{ki}$ and q_{ki} satisfy the following conditions:

b₁) $h_k(\cdot), l_k(\cdot) \in L_p(\Pi)$, $p \in (2, \infty)$, $p_{ki}, q_{ki} \in (1, \infty)$, $i = 1, 2$; $k = 1, 2$, if $n + m_1 = n + m_2 = 4$;

b₂) $h_k(\cdot) \in L_p(\Pi)$, $p \in (1, \infty)$, $l_k(\cdot) \in L_{\frac{n+m_2}{2}}(\Pi)$, $k = 1, 2$,

$$p_{k1}, q_{k1}, r_{k1} \in (1, \infty), p_{k2} \leq \frac{n + m_2}{n + m_2 - 4}, \quad (7)$$

$$q_{k2} < \frac{n + m_2}{n + m_2 - 4}, r_{k2} \leq \frac{4}{n + m_2 - 4}, \quad k = 1, 2, \quad (8)$$

if $n + m_1 = 4$, $n + m_2 > 4$;
 $b_3) h_k(\cdot) \in L_{\frac{n+m_1}{2}}(\Pi), l_k(\cdot) \in L_{\frac{n+m_2}{2}}(\Pi)$, $k = 1, 2$,

$$p_{k1} \leq \frac{n + m_1}{n + m_1 - 4}, p_{k2} \leq \frac{n + m_2}{n + m_2 - 4}, \quad k = 1, 2, \quad (9)$$

$$q_{k1} \leq \frac{4}{n + m_1 - 4}, q_{k2} \leq \frac{4(n + m_2)}{(n + m_2 - 4)(n + m_1)}, \quad k = 1, 2, \quad (10)$$

$$r_{k1} \leq \frac{4(n + m_1)}{(n + m_1 - 4)(n + m_2)}, r_{k2} \leq \frac{4}{n + m_2 - 4}, \quad k = 1, 2, \quad (11)$$

if $n + m_1 > 4$, $n + m_2 > 4$;

Theorem 2. *Let (2) and the condition 1 be fulfilled. Suppose that conditions II a) or II b) are valid. Then the assertion of Theorem 1 holds.*

2. Proof of the theorem on local solvability

In a Hilbert space H define a linear operator Λ as follows

$$\Lambda = \begin{pmatrix} 0 & I & 0 & 0 \\ -\Delta_{I_1}^2 + \Delta_{J_1} & 0 & 0 & 0 \\ 0 & 0 & 0 & I \\ 0 & 0 & -\Delta_{I_2}^2 + \Delta_{J_2} & 0 \end{pmatrix}, D(\Lambda) = W_{2,1}^{4,2} \times W_{2,1}^{2,1} \times W_{2,2}^{4,2} \times W_{2,2}^{2,1}.$$

Let us also define the nonlinear operator

$$F(t, w) = \begin{pmatrix} 0 \\ f_1(t, \cdot, v_1, v_3) \\ 0 \\ f_1(t, \cdot, v_1, v_3) \end{pmatrix}, \text{ where } w = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix}$$

In a Hilbert space H the problem (1), (2) can be written as an operator differential equation:

$$\left. \begin{aligned} w'(t) &= \Lambda w(t) + F(t, w(t)), \\ w(0) &= w_0, \end{aligned} \right\} \quad (12)$$

Let us provide a well-known theorem on the local solvability of the Cauchy problem in a Hilbert space H .

Theorem 3. *(see [4]) Let a linear operator Λ generate a strongly continuous contracting semigroup in the space H , the mapping $(t, w) \rightarrow F(t, w) : [0, T] \times H \rightarrow H$ satisfies the local Lipschitz condition, i.e. for any $t_1, t_2 \in [0, T]$, $w^1, w^2 \in H$*

$$\|F(t_1, w^1) - F(t_2, w^2)\|_H \leq c(\|w^1\|_H, \|w^2\|_H) \cdot \|w^1 - w^2\|_H,$$

where $c(\cdot, \cdot) \in C(R_+^2)$.

Then for any $w_0 \in \mathbf{H}$ there exists $T' > 0$ such that the problem (1), (3)-(6) has a unique solution $w \in C([0, T']; H)$. Moreover, if T_{\max} the length of the maximal interval of the existence of a weak solution is $w \in C([0, T_{\max}); H)$, then one of the following statements is true:

i) or $T_{\max} = +\infty$,

ii) or $\lim_{t \rightarrow T_{\max} - 0} \|w(t)\|_H = +\infty$.

If additionally $w_0 \in D(\Lambda)$, then $w \in C([0, T']; D(\Lambda)) \cap C^1([0, T']; H)$.

Using the definition of the space \mathbf{H} and the operator Λ , we obtain the following statement.

Lemma 1. *Linear operator Λ generates a strongly continuous contracting semigroup in the space \mathbf{H} .*

The following lemma is also true.

Lemma 2. *The mapping $F(t, w)$ is a bounded operator acting from $[0, T] \times \mathbf{H}$ to \mathbf{H} . The mapping $(t, w) \rightarrow F(t, w) : [0, T] \times \mathbf{H} \rightarrow \mathbf{H}$ satisfies the local Lipschitz condition, i.e. for any $t_1, t_2 \in [0, T]$, $w^1, w^2 \in \mathbf{H}$*

$$\|F(t_1, w^1) - F(t_2, w^2)\|_{\mathbf{H}} \leq c(\|w^1\|_{\mathbf{H}}, \|w^2\|_{\mathbf{H}}) \cdot \|w^1 - w^2\|_{\mathbf{H}},$$

where $c(\cdot, \cdot) \in C(R_+^2)$.

Proof. We will carry out the proof in the case when $n + m_k > 4$, $k = 1, 2$. The remaining cases are considered analogously.

Using the expression for $F(t, w)$, we obtain that

$$\begin{aligned} & \|F(t_1, w^1) - F(t_2, w^2)\|_{\mathbf{H}}^2 \leq \\ & \leq 2 \sum_{k=1}^2 \|f_k(t_1, x, v_1^1, v_3^1) - f_k(t_2, x, v_1^2, v_3^2)\|_{\mathbf{H}}^2 \leq G_{1k} + G_{2k} + G_{3k}, \end{aligned}$$

where

$$G_{1k} = c \int_{\Pi} \left| \int_0^1 f'_{kt}(t_1 + \tau(t_2 - t_1), x, v_1^1 + \tau(v_1^2 - v_1^1), v_3^1 + (v_2^2 - v_2^1)) \right|^2 d\tau |t_2 - t_1|^2 dx,$$

$$G_{2k} = c \int_{\Pi} \left| \int_0^1 f'_{kv_1}(t_1 + \tau(t_2 - t_1), x, v_1^1 + \tau(v_1^2 - v_1^1), v_3^1 + (v_2^2 - v_2^1)) \right|^2 d\tau |v_1^2 - v_1^1|^2 dx,$$

$$G_{3k} = c \int_{\Pi} \left| \int_0^1 f'_{kv_2}(t_1 + \tau(t_2 - t_1), x, v_1^1 + \tau(v_1^2 - v_1^1), v_3^1 + (v_2^2 - v_2^1)) \right|^2 d\tau |v_2^2 - v_2^1|^2 dx.$$

Using the condition **II** b₃) we have

$$\begin{aligned}
G_{1k} &\leq c \int_{\Pi} \int_0^1 [g_k(x) + |\tau v_1^1 + (1-\tau)v_1^2|^{p_{k1}} + |\tau v_2^1 + (1-\tau)v_2^2|^{p_{k2}}]^2 d\tau dx |t_2 - t_1|^2 \leq \\
&\leq \left[c_1 \int_{\Pi} g_k^2(x) dx + c_1 \int_0^1 \int_{\Pi} |\tau v_1^1 + (1-\tau)v_1^2|^{2p_{k1}} dx + \right. \\
&\quad \left. + c_1 \int_0^1 \int_{\Pi} |\tau v_2^1 + (1-\tau)v_2^2|^{2p_{k2}} dx \right] \cdot |t_2 - t_1|^2 \quad (13)
\end{aligned}$$

Taking into account the expression $W_{2,k}^{2,1} \subset L_{\frac{n+m_k}{n+m_k-4}}(\Pi)$, $k := 1, 2$ (see [3]) from (13) we obtain that

$$\begin{aligned}
G_{1k} &\leq C \left[1 + \int_0^1 \|\tau v_1^1 + (1-\tau)v_1^2\|_{W_{2,k}^{2,1}}^{2p_{k1}} d\tau + \int_0^1 \|\tau v_2^1 + (1-\tau)v_2^2\|_{L_2(\Pi)}^{2p_{k2}} d\tau \right] \cdot |t_2 - t_1|^2 \leq \\
&\leq C \left[1 + \|v_1^1\|_{W_{2,1}^{2,1}}^{2p_{k1}} + \|v_1^2\|_{W_{2,1}^{2,1}}^{2p_{k1}} + \|v_2^1\|_{W_{2,2}^{2,1}}^{2p_{k2}} + \|v_2^2\|_{W_{2,2}^{2,1}}^{2p_{k2}} \right] \cdot |t_2 - t_1|^2. \quad (14)
\end{aligned}$$

Similarly using the condition **II** b_3) we have

$$\begin{aligned}
G_{2k} &\leq c \int_{\Pi} \int_0^1 [h_k(x) + |\tau v_1^1 + (1-\tau)v_1^2|^{q_{k1}} + |\tau v_2^1 + (1-\tau)v_2^2|^{q_{k2}}]^2 |v_1^2 - v_1^1|^2 d\tau dx \leq \\
&\leq \left[c_1 \left(\int_{\Pi} h_k^{2\alpha'_k}(x) dx \right)^{1/\alpha'_k} + \left(\int_{\Pi} |\tau v_1^1 + (1-\tau)v_1^2|^{2q_{k1}\alpha'_k} dx \right)^{1/\alpha'_k} + \right. \\
&\quad \left. + \left(\int_{\Pi} |\tau v_2^1 + (1-\tau)v_2^2|^{2q_{k2}\alpha'_k}(x) dx \right)^{1/\alpha'_k} \right] \cdot \left[\int_{\Pi} |v_1^2 - v_1^1|^{2\alpha_k} dx \right]^{1/\alpha_k}, \quad (15)
\end{aligned}$$

where $\alpha_k = \frac{n+m_1}{n+m_1-4}$, $\alpha'_k = \frac{n+m_1}{4}$.

By virtue of (10) $2q_{k1}\alpha'_k \leq \frac{2(n+m_1)}{n+m_1-4}$, $2q_{k2}\alpha'_k \leq \frac{2(n+m_2)}{n+m_2-4}$, $k = 1, 2$, and thus

$$\left[\int_{\Pi} |v_1^2 - v_1^1|^{2\alpha_k} dx \right]^{1/\alpha_k} \leq c \|v_1^2 - v_1^1\|_{W_{2,1}^{2,1}}^2, \quad (16)$$

$$\begin{aligned}
&\left(\int_{\Pi} |\tau v_1^1 + (1-\tau)v_1^2|^{2q_{k1}\alpha'_k} dx \right)^{1/\alpha'_k} \leq \\
&\leq c \|\tau v_1^1 + (1-\tau)v_1^2\|_{W_{2,1}^{2,1}}^{2q_{k1}} \leq C \left(\|v_1^1\|_{W_{2,1}^{2,1}}^2 + \|v_1^2\|_{W_{2,1}^{2,1}}^2 \right)^{q_{k1}}, \quad (17)
\end{aligned}$$

$$\left(\int_{\Pi} |\tau v_2^1 + (1-\tau)v_2^2|^{2q_{k2}\alpha'_k} dx \right)^{1/\alpha'_k} \leq$$

$$\leq c \left\| \tau v_2^1 + (1 - \tau) v_2^2 \right\|_{W_{2,2}^{2q_{k2}}}^2 \leq C \left(\left\| v_2^1 \right\|_{W_{2,2}^{2q_{k2}}}^2 + \left\| v_2^2 \right\|_{W_{2,2}^{2q_{k2}}}^2 \right)^{q_{k2}}. \quad (18)$$

From (14)-(18) it follows

$$G_{2k} \leq C \left[1 + \left\| v_1^1 \right\|_{W_{2,1}^{2q_{k1}}}^2 + \left\| v_1^2 \right\|_{W_{2,1}^{2q_{k1}}}^2 + \left\| v_2^1 \right\|_{W_{2,2}^{2q_{k2}}}^2 + \left\| v_2^2 \right\|_{W_{2,2}^{2q_{k2}}}^2 \right] \cdot \left\| v_1^2 - v_1^1 \right\|_{W_{2,1}^{2q_{k1}}}^2. \quad (19)$$

Taking into account (9)-(11) we similarly obtain

$$G_{3k} \leq C \left[1 + \left\| v_1^1 \right\|_{W_{2,1}^{2r_{k1}}}^2 + \left\| v_1^2 \right\|_{W_{2,1}^{2r_{k1}}}^2 + \left\| v_2^1 \right\|_{W_{2,2}^{2r_{k2}}}^2 + \left\| v_2^2 \right\|_{W_{2,2}^{2r_{k2}}}^2 \right] \cdot \left\| v_1^2 - v_1^1 \right\|_{W_{2,1}^{2r_{k1}}}^2. \quad (20)$$

Thus, in view of (14), (19),(20) we obtain that

$$\left\| F(t_1, w^1) - F(t_2, w^2) \right\|_{\mathbb{H}} \leq c \left(\left\| w^1 \right\|_{\mathbb{H}}, \left\| w^2 \right\|_{\mathbb{H}} \right) \left\| w^2 - w^1 \right\|_{\mathbb{H}}$$

From Lemmas 1 and 2 it follows that for the problem (2.12) all the conditions of Theorem 3, on local solvability are satisfied.

3. Solvability "as a whole" of the mixed problem for systems of semilinear hyperbolic equations of the fourth order

In the domain $Q_T = [0, T] \times \Pi$ let us consider the mixed problem

$$\left. \begin{aligned} u_{1tt} + \Delta_{I_1}^2 u_1 - \Delta_{J_1} u_1 + |u_1|^{p_1-1} |u_2|^{p_2+1} u_1 &= f_1(t, x), \\ u_{2tt} + \Delta_{I_2}^2 u_2 - \Delta_{J_2} u_2 + |u_1|^{p_1+1} |u_2|^{p_2-1} u_2 &= f_2(t, x), \end{aligned} \right\} \quad (21)$$

with the boundary conditions

$$u_k(t, x_1, x_2, \dots, x_i, \dots, x_n) = 0, \quad x_i = 0, x_i = 1, k = 1, 2; \quad i = 0, 1, \dots, n; \quad (22)$$

$$\Delta_{I_k} u_k(t, x_1, x_2, \dots, x_i, \dots, x_n) = 0, \quad x_i = 0, x_i = 1, i \in I_k, \quad k = 1, 2; \quad (23)$$

and the initial conditions

$$u_k(0, x) = \varphi_k(x), \quad u_{kt}(0, x) = \psi_k(x), \quad x \in \Pi, \quad k = 1, 2, \quad (24)$$

where

$$n + m_2 \leq 4, \quad p_j \geq 0, j = 1, 2, \quad (25)$$

$f_k(t, x)$, $k = 1, 2$ are real functions $t \in [0, \infty)$, $x \in \Pi$ and

$$f_k(\cdot) \in L_2(0, T; \Pi), \quad k = 1, 2. \quad (26)$$

Theorem 4. *Let all the conditions (25) and (26) be fulfilled. Then for any $((\varphi_1, \psi_1), (\varphi_2, \psi_2)) \in W_{2,1}^{2,1} \times L_2(R^n) \times W_{2,2}^{2,1} \times L_2(\Pi)$ and $T > 0$ the mixed problem (21)-(24) has a unique solution.*

$$(u_1, u_2) \in C \left([0, T]; W_{2,1}^{2,1} \times W_{2,2}^{2,1} \right) \cap C^1 \left([0, T]; L_2(\Pi) \times L_2(\Pi) \right).$$

Proof. In view of Theorem 1, the problem (1)-(3) has a local solution and for the possibility of a global extension of this solution it is sufficient to perform the following a priori estimation:

$$E(t) = \sum_{k=1}^2 \left[\int_{\Pi} |\Delta_k u_{k\tau}(t, x)|^2 dx + \int_{\Pi} |\nabla_{J_k} u_k(t, x)|^2 dx + \int_{\Pi} |u'_{kt}(t, x)|^2 dx \right] \leq C, \quad t \in [0, T_{\max}). \quad (27)$$

Let us multiply both sides of the first equation of the system (21) by $(p_1 + 1) u_{1t}(t, x)$, and the second equation by $(p_2 + 1) u_{2t}(t, x)$ and integrate the obtaining identity over the domain $Q_T = [0, t] \times \Pi$:

$$\begin{aligned} & \sum_{k=1}^2 \frac{p_k + 1}{2} \left[\int_{\Pi} |u_{k\tau}(t, x)|^2 dx + \int_{\Pi} |\Delta_k u_k(t, x)|^2 dx + \int_{\Pi} |\nabla_{J_k} u_k(t, x)|^2 dx \right] + \\ & \quad + \int_{\Pi} |u_1(\tau, x)|^{p_1+1} |u_2(\tau, x)|^{p_2+1} dx d\tau = \\ & = \sum_{k=1}^2 \frac{p_k + 1}{2} \left[\int_{\Pi} |\psi_k(x)|^2 dx + \int_{\Pi} |\Delta_{I_k} \varphi_k(x)|^2 dx + \int_{\Pi} |\nabla_{J_k} \varphi_k(x)|^2 dx \right] + \\ & \quad + \sum_{k=1}^2 (p_k + 1) \int_0^t \int_{\Pi} f(\tau, x) \cdot u_{k\tau}(\tau, x) dx d\tau. \end{aligned}$$

Further, applying the Hölder inequality and taking (25), (26) into account, we have:

$$\begin{aligned} & \sum_{k=1}^2 \frac{p_k + 1}{2} \left[\int_{\Pi} |u_{k\tau}(t, x)|^2 dx + \int_{\Pi} |\Delta_k u_k(t, x)|^2 dx + \int_{\Pi} |\nabla_{J_k} u_k(t, x)|^2 dx \right] + \\ & \quad + \int_{\Pi} |u_1(t, x)|^{p_1+1} |u_2(t, x)|^{p_2+1} dx d\tau \leq C + \sum_{k=1}^2 \frac{p_k + 1}{2} \int_0^t \int_{\Pi} |u_{k\tau}(\tau, x)|^2 dx d\tau, \end{aligned}$$

where

$$\begin{aligned} C = & \sum_{k=1}^2 \frac{p_k + 1}{2} \left[\int_{\Pi} |\psi_k(x)|^2 dx + \int_{\Pi} |\Delta_{I_k} \varphi_k(x)|^2 dx + \int_{\Pi} |\nabla_{J_k} \varphi_k(x)|^2 dx \right] + \\ & + \sum_{k=1}^2 \frac{p_k + 1}{2} \int_0^T \int_{\Pi} |u_{k\tau}(\tau, x)|^2 dx d\tau. \end{aligned}$$

Here applying Gronwall's lemma (see [5]) we obtain the estimation (27).

References

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